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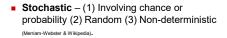
Modeling our measurements

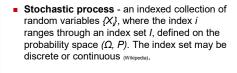
- Repetition of the same experiment will not lead to the exact same response.
- Example: The spike train of a neuron in response to stimuli is different...
- Typically we would like to know:
 - When is something unexpected?
 - What are the "normal" values?
- Thus, analyzing a sequence of measurements requires modeling of the underlying process.

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Stochastic process Definition





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Stochastic process Special cases

- A stochastic process defined over the time interval domain is called a time series.
 - Example of a continuous time series: temperature in BIU throughout the day.
 - Example of a discrete time series:
 amount of rain in BIU on a specific day on of the year.
 - Example of a quantized discrete time series: did rain fall in BIU on a specific day of the year?
 - Example of discrete non-time series:
 height of people entering Gonda building each day
- A stochastic process defined over the space interval domain is called a random field.

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Stationary processes Strict / Strong

 A stochastic process whose unconditional joint probability distribution does not change when shifted in its index (typically time).

 $F_X(x_{t_1+ au},\ldots,x_{t_n+ au})=F_X(x_{t_1},\ldots,x_{t_n}) \quad ext{for all } au,t_1,\ldots,t_n\in\mathbb{R} ext{ and for all } n\in\mathbb{N}$



- Probability density function (PDF) p(x) describes the distribution of a continuous random variable, x.
 - $\int_{-\infty}^{\infty} p(x) dx = 1$
- Cumulative function: $F(x) = \int_{-\infty}^{x} p(y) dy$ • Survival function : $1 - F(x) = \int_{x}^{\infty} p(y) dy$
- Nth order stationary process is defined for all n={1, ... N}

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Stationary processes Wide-sense / Weak

- A weak or wide-sense stationary (WSS) process only is a second degree stationary process.
- Equal mean value

$$E(X(t)) = \mu_x(t) = \mu_x(t+\tau) \quad \forall \tau \in \mathbb{R}$$

• Covairance dependent only on index difference

$$E(X(t_1) - \mu_X(t_1) \cdot (X(t_2) - \mu_X(t_2)) = Cov(X(t_1), X(t_2))$$

$$= Cov(X(t_1 + \tau), X(t_2 + \tau)) = Cov(X(t_1 - t_2), 0)$$



Stationary processes - examples

- Stationary example: Sequence of L/R button presses. Each press has a 90% probability of being in the same direction as its predecessor.
 - Stationary despite strong temporal covariance.
- Non-stationary example: Amount of rainfall for each day of the year.
 - In many cases long term changes may be removed using de-trending techniques.

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Ergodicity



 If averaging over time and space are equal the process is ergodic.



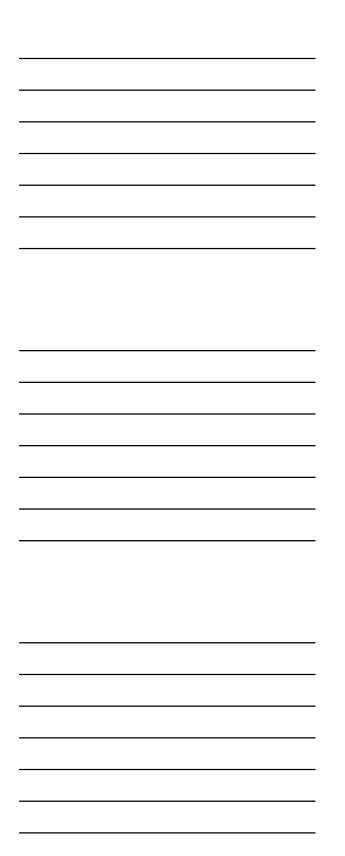
• Ergodicity is usually described in terms of properties of an ensemble of objects.



■ Example: Finding out how people spend their spare time. Sampling one person over 1000 days would yield the same result as sampling 1000 people once in an ergodic system.

Reading material:

com/news/What-is-ergodicity-15686.shtml





Ergodic & stationary processes

- In an ergodic process, the following are equal
 - Averaging across repeated trials
 - Averaging across time for a single trial
- An ergodic process is always stationary, the reverse may not be true
- A stationary process is ergodic if samples that are far enough in time are independent (asymptotic independence).

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Overview

- Stochastic processes
- Point processes
- Appendix: extracellular recording

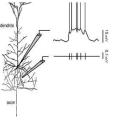
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Intracellular vs. Extracellular neuronal potentials

• Intracellular soma







Extracellular spike trains

- Transformation from a continuous recording to a series of discrete **timestamps**.
- Is all the information contained in the **timing** of the spikes?
- What are we losing?
 - Spike shapes

 - Non spiking activity
 Sub-threshold activity

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Time series & Point processes

- Continuous time series
 - Electroencephalogram (EEG)Electromyogram (EMG)

 - Intracellular potential

(Note: "Continuous" is the common term but is misleading since it applies to both discrete and continuous in time)

- Stochastic point processes
 - Neural action potentials
 - Heart beats
 - Behavioral events

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Delta functions (reminder)



 Dirac's delta function $\delta(x-\tau)=0\ x\neq\tau$





Kronecker's delta function



 $\delta(n-k) = \begin{cases} 1 & n=k \\ 0 & n \neq k \end{cases} \sum_{n=-\infty}^{\infty} \delta(n) = 1$

		
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Point process



 The spike train is represented by the sum of Dirac's delta functions at its firing times (t_i)

$$\rho(t) = \sum_{i=1}^{n} \delta(t - t_i)$$

Point processes are unitary events in time.
 The actual values in time are meaningless.

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Properties of a single spike train

- Firing rate
- Response to events
- Firing pattern
- Exact timing
- Entropy

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The neural transformation



 $x(t) \rightarrow Sensors \rightarrow r(t) \rightarrow Spike Generator \rightarrow \rho(t)$



x(t) = external signal



 $\rho(t)$ = actual spikes



We observe $\rho(t)$, and we need to estimate r(t) (eventually we will use this to estimate x(t))

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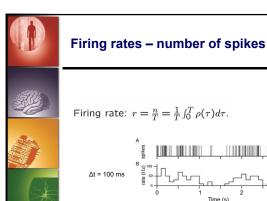


Firing rate definition

- There are different definitions to firing rate
 - r rate over the whole period T also called spike count rate
 - <r> rate averaged over all the trials, also called average firing rate
 - r(t) trial average rate over a short period (∆t→0)

and they are constantly mixed...

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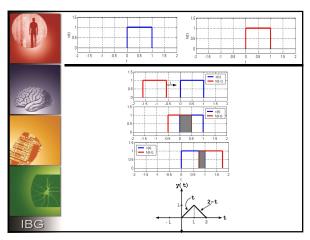
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Convolution

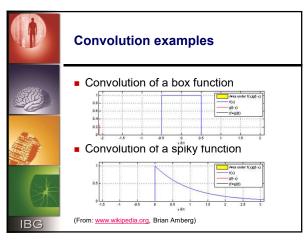
- Convolution is an operator which takes two functions f and g and produces a third function that represents the overlap between f and a reversed version of g.
- $\qquad \qquad \text{Continuous:} \ \ (f*g)(t) = \int f(\tau)g(t-\tau)\,d\tau$
- $\qquad \text{Discrete: } (f*g)(m) = \sum_n f(n)g(m-n)$

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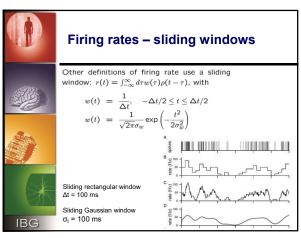


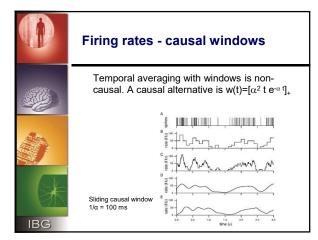


Convolution & Moving average

- A convolution is a general **moving average** when the averaging function integral is 1.
- In that case it functions as a **smoothing** function.
- When the averaging function is square it will function as regular mean using overlapping bins.
- Non-square functions enable **emphasis** of parts of the window.

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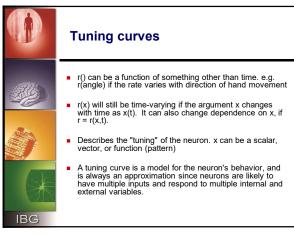


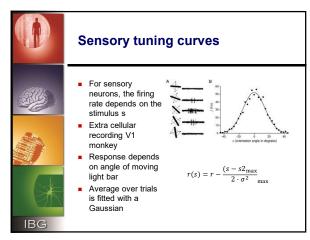
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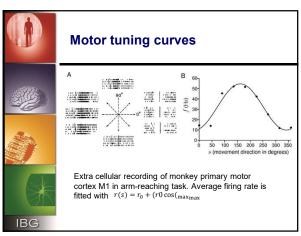


Smoothing & Convolution

- Smoothing and convolution pitfalls
 - Introduces spurious correlations over time
 - Hidden assumption about smoothness of the external sensory or motor data
 - Edge effects: what happens at the start and end of the data?
 - Phase lag: peaks of smoothed data may occur later than the peaks in the original data. True for non-symmetric kernels and all causal filters









Spike count variability

- Tuning curves model average behavior.
- Deviations of individual trials are given by a noise model.
 - Additive noise is independent of stimulus r(s) = f(s) + ξ
 - Multiplicative noise is proportional to stimulus



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Signal to noise ration

■ Power of the signal (mean square)

Discrete $\frac{1}{N}\sum_{i=1}^{N}x_i^2$ Continuous $\frac{1}{T}\int_0^T x_i^2$

■ Amplitude of the signal (root mean square)

Discrete $\sqrt{\frac{1}{N}\sum_{i=1}^{N}x_i^2}$ Continuous $\sqrt{\frac{1}{T}\int_0^T x_i^2}$

- $\begin{tabular}{ll} \blacksquare & The signal to noise ratio (SNR) may be calculated \\ & directly: $\frac{ms(signal)}{ms(signal)}$ or $(\frac{rms(signal)}{rms(signal)})^2$ \\ \end{tabular}$
- However, typically a decibel (dB) scale is used...

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Decibel (dB)



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■ The **decibel** (**dB**) is a logarithmic measure of the ratio between two quantities:

 $\mathsf{SNR}_{\mathsf{dB}} = \ 10 log_{10} \ \frac{ms(signal)}{ms(signal)} \ \ or \ 20 log_{10} \ \frac{rms(signal)}{rms(signal)}$

- SNR of 3 dB is roughly double the power while 10 dB is ten times the power.
- SNR of 6 dB is roughly double the amplitude while 20 dB is ten times the power.



